

Facilitating The Internet Of Things With Policy Programming

Supplementing the works presented in:

"Integrated development environment for debugging policy-based applications in wireless sensor networks"

...and lessons learned since.

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Main Research and Development Products

- Policy IDE
 - Real-time debugging of policy programming
 - GUI
- TOSServ
 - Centralized TOSSIM Service
- Finger2IPv6
 - Policy programming could now occur on real wireless sensor devices, using IPv6

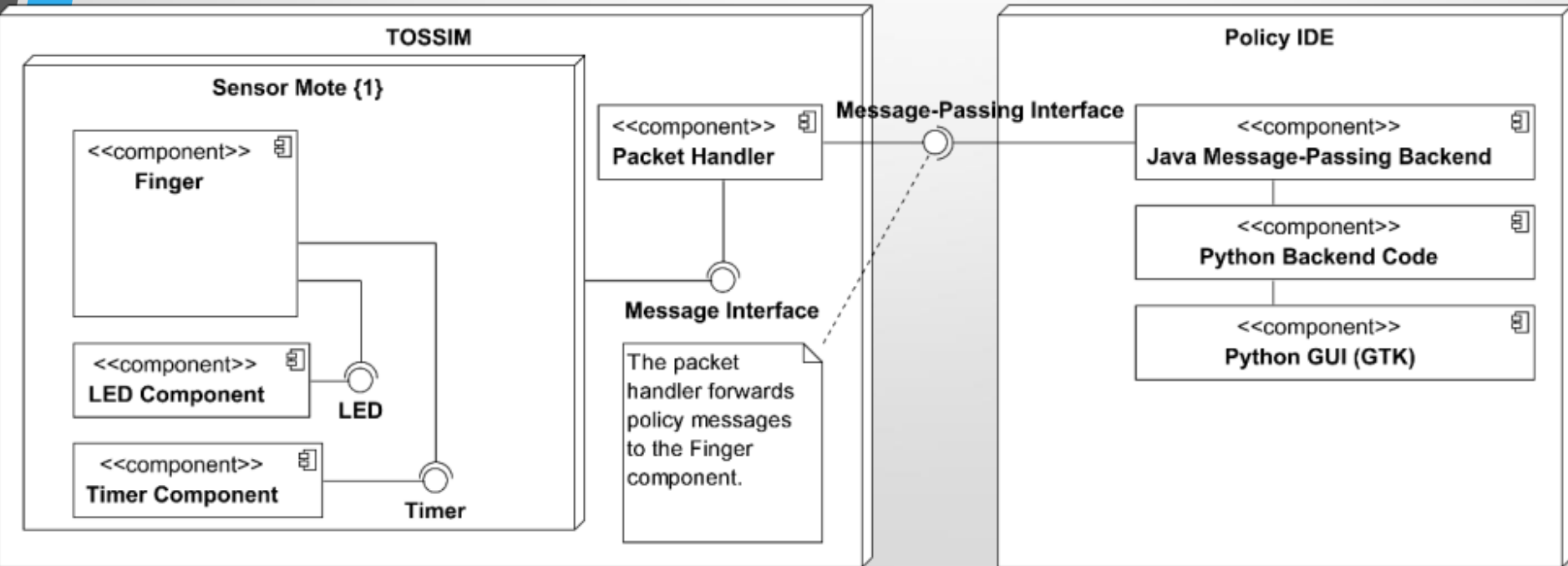
Code available on GitHub (2 dev. branches):

github.com/drspangle/tinyos-main/tree/Finger2IPv6

github.com/drspangle/tinyos-main/tree/TOSServ

Policy IDE

- Real-time debugging of policy programming using packet injection became possible.
- Main thrust of paper.
- Debug messages collected from TOSSIM, displayed on GUI in real time.



Policy IDE

- Viewing these messages and manipulating policies on simulated devices allowed introspection into the results of policies.
- Policy programming was conducted using emulated sensor motes running the Finger2 policy engine core (by Themistoklis Bourdenas).

What's the point of policy programming?

- If, then – logical inferences:
 - Something like a rule-based system.
- Classically useful for network security:
 - Firewalls.
 - IDS.
- Special niche in the tinyOS world.

Our special niche in tinyOS...

- Allows for extensible control logic.
- tinyOS is all about creating components:
 - Pseudo-objects with events and actions.
- ... but if you want to change anything except a variable, you have to re-flash the entire binary onto the device.
- Policy programming lets you tie it all together.
- Not as useful for very simple if conditions.
 - Great for chains of inference.
 - Great for making software robust to changing circumstances.

Leveraging the Event Driven System

- Policy programming is an application development platform that lets you sandwich together the best of two worlds:
 - Event driven architecture of tinyOS.
 - 'Dumb' functions.

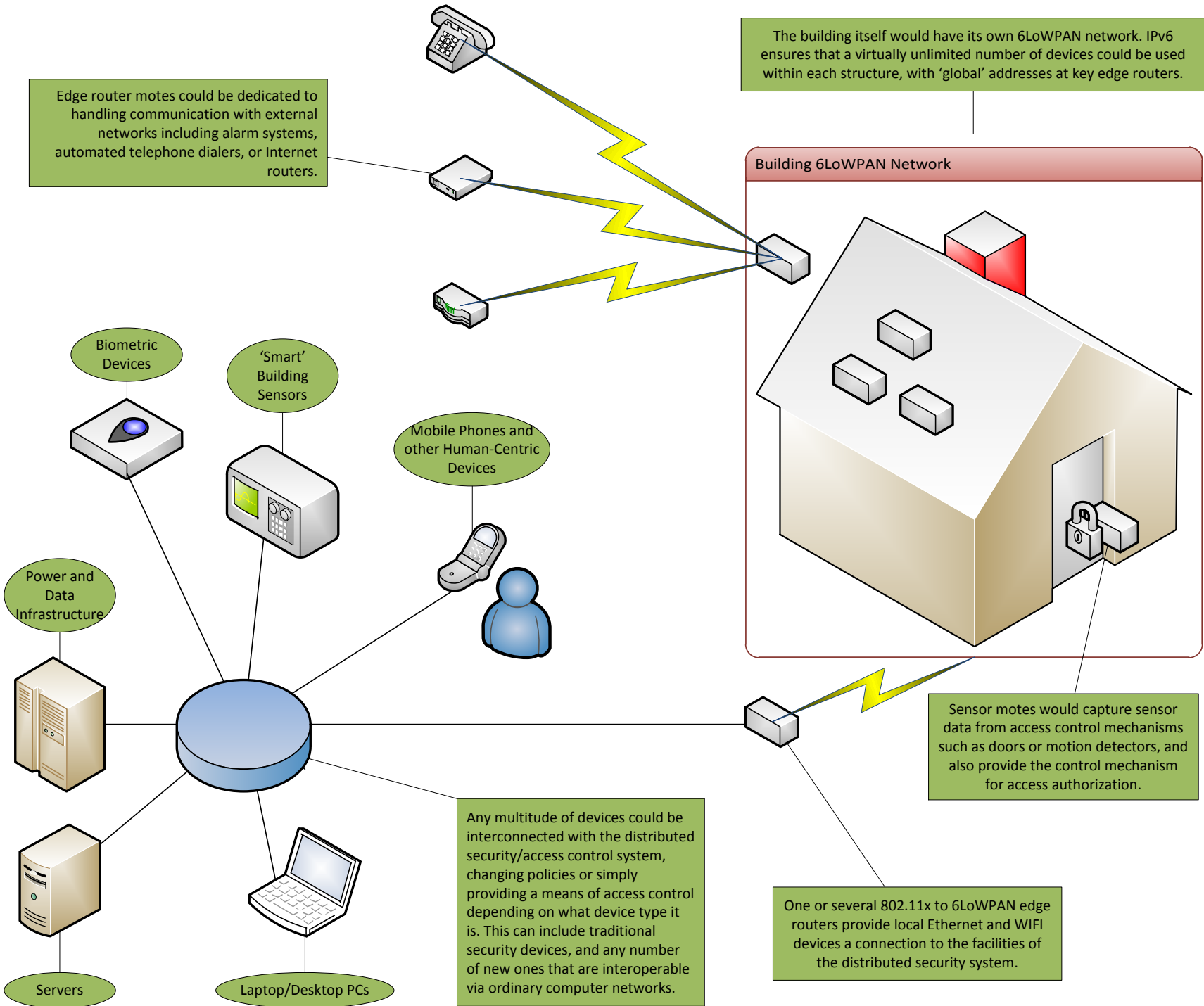
Why a Policy IDE became a logical necessity...

- Policy programming is essentially an informal programming language.
- Policies quickly become complicated
 - Chains of inference can get long, fast.
- Debugging and testing...
 - Facilities for triggering events, so actions can be evaluated.
 - Facilities for viewing the output in an easy way.
 - Rejoice - No more manual memory introspection!

Making Policy-Based Applications

Key design principles:

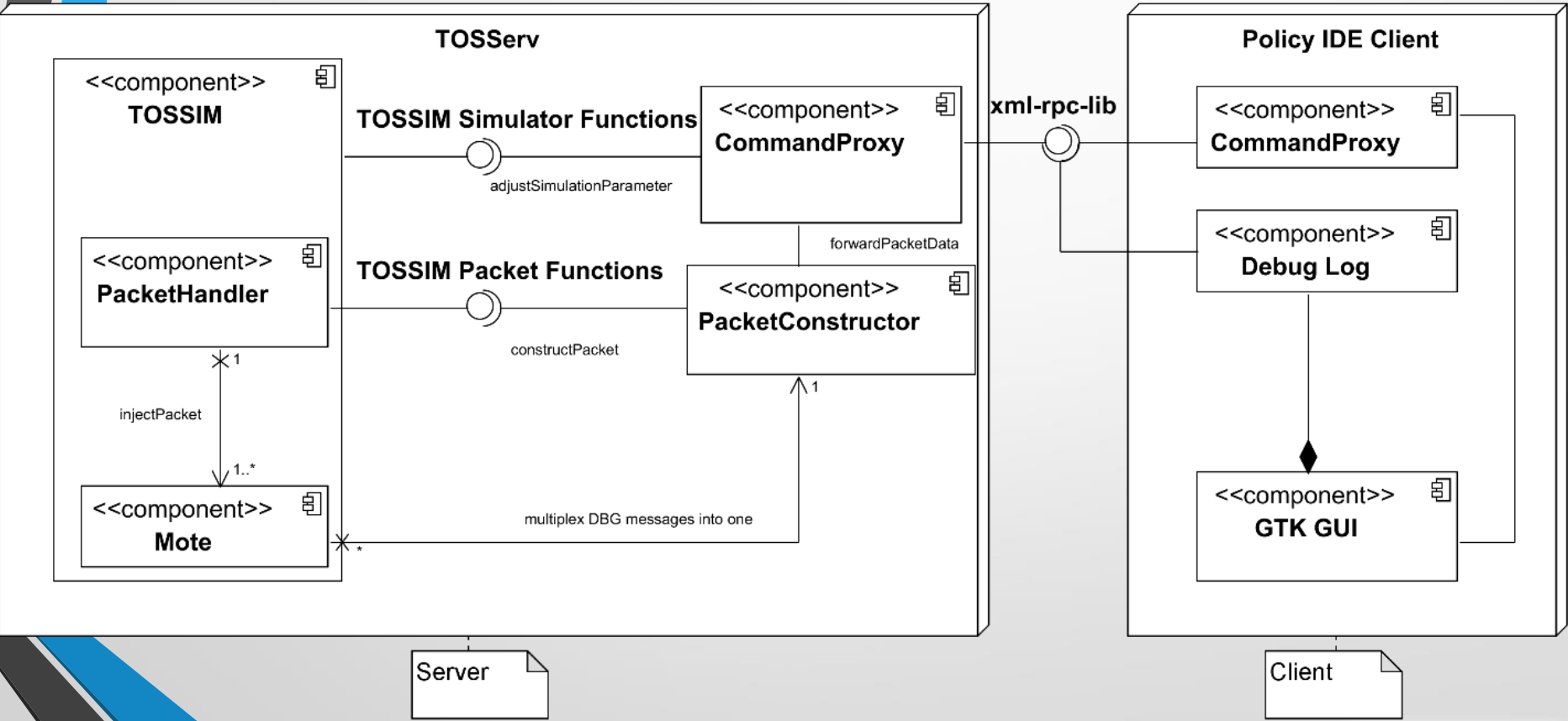
- Reprogramming over the air can be avoided by introducing new policies, and/or updating old ones.
- Policies can be chained to one another, providing a robust event-driven rule-based architecture for larger system designs.
- Policies can be used in conjunction with highly optimized low-level nesC code units as extensible control logic.



TOSServ

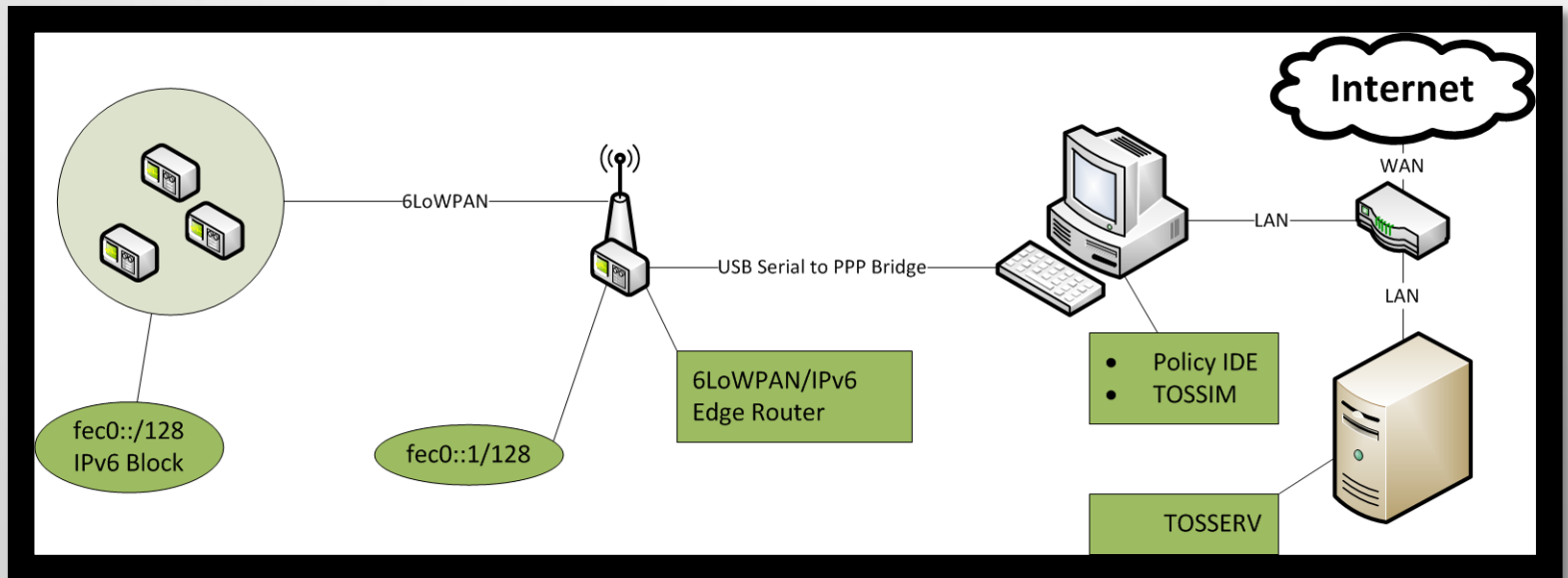
- Allows TOSSIM to sit in its own environment, happy with it's old version of gcc 3 and peculiar build chain.
- Distributed from the Policy IDE client using xml-rpc (Python).
- Needs further development.

TOSServ



Transitioning to IPv6

The basic picture laid out...



Finger2IPv6

- Binding the Finger2 policy engine core with blip (Berkeley Low-Power Internet Stack).
- Finger2 was previously bound to AMPacket, to work with TOSSIM.
- TOSSIM doesn't support blip (due to low-level code optimizations, very convenient but quirky tinyOS API hacks).

Finger2IPv6

- Now we can do what Policy IDE does from the command line.
 - Command-line interpreter similar to Python, except for Policy Programming.
 - Load, delete, enable, disable, and test policies.
- Next steps:
 - GUI integration.
 - A new language? Policy Definition Language.
 - Self-discovery and network policy discovery.